

RESEARCH ARTICLE

Genetic Algorithm-Based Intelligent Parameter Optimization for Apache Hadoop MapReduce Systems: A Machine Learning and Evolutionary Computing Approach

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Abstract

Apache Hadoop MapReduce remains a foundational distributed computing platform, yet its performance is critically dependent on proper configuration of 190+ interdependent parameters. Manual parameter tuning is prohibitively time-consuming and suboptimal, while existing automated approaches suffer from excessive computational overhead. This paper presents a comprehensive intelligent optimization framework integrating genetic algorithms (GA) with genetic programming (GP), machine learning classification, ensemble methods, and reinforcement learning to automatically optimize Hadoop MapReduce configuration parameters. The proposed approach employs genetic programming to derive mathematical objective fitness functions from empirical MapReduce job execution data, subsequently applying parallel genetic algorithm optimization with advanced selection, crossover, and mutation operators to efficiently search the parameter space. Comprehensive experimental evaluation on a 4-node Hadoop 3.3.0 cluster demonstrates substantial performance improvements: WordCount applications achieve 63-69% execution time reduction across 1GB-10GB datasets, TeraSort achieves 52-55% improvement, and Grep/Index applications achieve 47-56% speedup. The framework optimizes eight critical parameters through 200 generations with population size 15, achieving convergence within 40,000 fitness evaluations. The research contributes novel fitness function generation through genetic programming, parallel GA implementation for parameter optimization, ML-based parameter importance ranking, ensemble prediction models, and dynamic parameter adjustment mechanisms.

Keywords: Genetic Algorithm, Genetic Programming, Hadoop MapReduce, Parameter Optimization, Machine Learning, Evolutionary Computing, Big Data Performance, Configuration Tuning, Fitness Function Engineering, Ensemble Methods, Reinforcement Learning, Distributed Computing.

1. Introduction and Motivation

1.1 Background and Context

The exponential growth in data generation across global organizations has established Apache Hadoop MapReduce as a foundational platform for large-scale distributed data processing[1]. Modern data centers deploy Hadoop clusters processing petabytes of data daily across diverse applications including financial analytics, scientific computing, healthcare informatics, social media analysis, and e-commerce operations[2]. The MapReduce programming model, introduced by Dean and Ghemawat, revolutionized distributed

computing by enabling automatic parallelization and fault tolerance[3].

However, Hadoop's performance is predominantly determined by configuration parameter settings rather than algorithmic complexity. The Hadoop framework exposes over 190 configuration parameters controlling

- Task Execution Parallelism: Maximum map/reduce task counts per node, parallel task execution limits, speculative execution strategies
- Memory Resource Management: JVM

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- heap allocation, buffer sizes for map/reduce operations, cache memory configurations
- Input/Output Optimization: Disk spill thresholds, sort buffer dimensions, compression strategies, I/O buffering
- Network Communication: Shuffle phase parallelism, parallel copy thread counts, network timeout configurations
- Data Locality: Block replication factors, rack awareness policies, data placement strategies

Despite these parameters' critical importance, most Hadoop deployments operate with default configurations, resulting in suboptimal performance[4]. Manual parameter tuning requires extensive domain expertise, empirical profiling, and iterative testing—a process consuming weeks or months while consuming 20-30% of total job execution time.

1.2 Problem Statement and Research Gaps

The Hadoop parameter optimization problem is fundamentally challenging

1. Exponential Configuration Space: 190+ parameters with varying ranges create a configuration space exceeding possible combinations, rendering exhaustive search computationally infeasible
2. Complex Parameter Interdependencies: Parameters interact non-linearly; changing one parameter affects the optimal value of others
3. Workload-Dependent Optimization: Optimal configurations differ significantly for CPU-intensive (WordCount) versus I/O-intensive (Sort, Index) applications
4. Dynamic Cluster Conditions: Cluster resource availability, network conditions, and system load vary over time, yet most optimization approaches provide static configurations
5. Multi-Objective Optimization: Optimization requires balancing throughput, latency, resource utilization, and energy consumption

Existing approaches exhibit critical limitations[5]

- Manual Tuning: Expert judgment without systematic exploration; prone to suboptimal configurations
- Exhaustive Search: Computationally

infeasible; requires 20-30% of job execution time for configuration generation

- Simple Machine Learning: Random forests, SVM, and linear regression models fail to capture non-linear parameter relationships
- Single-Objective Optimization: Parameterized methods (simulated annealing, particle swarm) often converge prematurely to local optima

1.3 Research Contributions and Innovations

This paper presents six primary research contributions

Contribution 1: Genetic Programming Derived Fitness Functions Develops novel approach generating mathematical fitness functions through genetic programming analysis of empirical MapReduce job execution data. Functions automatically capture non-linear relationships between eight critical parameters and job completion time.

Contribution 2: Advanced Genetic Algorithm Implementation Implements sophisticated parallel genetic algorithm with roulette wheel selection (proportional fitness-based), single-point crossover (20% crossover rate), and adaptive mutation (10% mutation rate) operators. Population size 15 with 200 generations achieves convergence within 40,000 fitness evaluations.

Contribution 3: Machine Learning-Enhanced Parameter Selection Applies feature importance ranking using random forest and gradient boosting to identify critical parameters from 190+ candidate parameters. Reduces parameter space from 190 to 8 parameters with 98% variance explained.

Contribution 4: Ensemble Prediction Mechanisms Develops ensemble learning models (random forest, gradient boosting, XGBoost) for predicting job execution time given parameter configurations. Ensemble approach achieves prediction accuracy.

Contribution 5: Reinforcement Learning-Based Dynamic Adaptation Implements Q-learning mechanism enabling runtime parameter adjustment based on cluster conditions. Adapts recommendations to varying workload types and resource availability.

Contribution 6: Comprehensive Experimental Validation Conducts extensive evaluation across four diverse MapReduce applications (WordCount, Grep, TeraSort, Index) with 1GB-10GB datasets,

demonstrating 47-69% execution time improvement over default configurations.

1.4 Key Performance Achievements

- WordCount: 63-69% execution time reduction across dataset sizes
- TeraSort: 52-55% execution time improvement
- Grep: 47-56% performance improvement
- Index: 44-52% speedup
- Convergence: 40,000 fitness evaluations (200 generations \times 200 chromosomes)
- Fitness Function Quality: Derived equations achieve match to actual execution times

1.5 Paper Organization

This paper is organized as follows: Section 2 reviews related work in Hadoop optimization, genetic algorithms, and machine learning; Section 3 presents the comprehensive framework architecture including genetic programming, genetic algorithms, ensemble learning, and reinforcement learning components; Section 4 describes experimental methodology and cluster setup; Section 5 presents detailed experimental results; Section 6 provides discussion and comparative analysis; Section 7 outlines practical implementation considerations; Section 8 concludes with future research directions.

2. Literature Review and Related Work

2.1 Hadoop Parameter Tuning and Optimization

Early Hadoop optimization focused on manual parameter tuning guided by domain expertise[6]. Reza et al.[7] identified eight critical Hadoop parameters through empirical analysis: mapreduce.task.io.sort.mb, mapreduce.task.io.sort.factor, mapred.compress.map.output, mapreduce.job.reduces, mapreduce.map.sort.spill.percent, mapreduce.tasktracker.map.tasks.maximum, mapreduce.tasktracker.reduce.tasks.maximum, and mapreduce.reduce.shuffle.input.buffer.percent.

Recent approaches employ computational optimization

- Profile-Based Tuning: Herodotou et al.[8] proposed Starfish system conducting runtime profiling and prediction, but introduces 15-20% overhead
- Machine Learning Methods: Support

vector regression and random forests achieve 15-18% prediction error[9], insufficient for critical applications

- Parameter Clustering: Bei et al.[10] propose kernel K-means clustering for parameter selection, reducing search space from 190 to 20 parameters

2.2 Genetic Algorithms for Optimization

Genetic algorithms, pioneered by Holland[11], are evolutionary algorithms inspired by natural selection processes. GAs maintain advantages over traditional optimization for complex problems[12]

1. Multi-parameter simultaneous optimization without explicit objective function gradients
2. Parallelizable search exploring multiple regions concurrently, reducing local optimum entrapment
3. Robustness in non-linear domains with discontinuous, time-varying fitness landscapes
4. Explicit information exchange through crossover enabling offspring to inherit beneficial traits from both parents

Parallel GA implementations include[13]

- Master-Slave Model: Master maintains population; slaves evaluate fitness in parallel
- Island Model: Multiple subpopulations evolve independently with periodic migration
- Fine-Grained Model: Grid-based parallel evaluation of candidate solutions

2.3 Genetic Programming

Genetic Programming extends genetic algorithms to automatic program synthesis[14]. John Koza pioneered GP enabling automatic discovery of mathematical functions and programs[15]. GP operates on tree-structured representations where

- Terminals: Input variables and constants
- Functions: Arithmetic operations (+, -, \times , \div), conditional operations, logical operators

GP-derived functions can capture complex relationships without explicit problem specification. Recent applications include

- Physics-informed neural networks incorporating GP-derived equations[16]
- Automated feature engineering through symbolic regression[17]

- Real-time control system optimization[18]

2.4 Machine Learning for Parameter Selection

Feature importance ranking identifies critical parameters from high-dimensional spaces

- Permutation Feature Importance: Measures performance degradation when features are randomly shuffled[19]
- SHAPValues: Provides local interpretability for model predictions through coalitional game theory[20]
- Gradient-Based Feature Importance: Computed from gradient information in tree-based models[21]

Random forest feature importance is calculated as

$$FI_j = \frac{\sum_t n_t \cdot IG_t(j)}{\sum_t n_t}$$

where n_t is samples in node j , $IG_t(j)$ is information gain from splitting on feature j .

2.5 Ensemble Learning Methods

Ensemble methods combine multiple learners to improve prediction accuracy

- Random Forest: Bagging with random feature subsets at each split; reduces overfitting[22]
- Gradient Boosting: Sequential trees minimizing residuals; achieves state-of-the-art accuracy[23]
- XGBoost: Regularized gradient boosting with second-order derivatives; handles non-linear relationships[24]

Ensemble predictions combine base learners through:

$$\hat{y} = \frac{1}{M} \sum_{m=1}^M f_m(x)$$

where $f_m(x)$ represents individual learner predictions.

2.6 Reinforcement Learning in Distributed Systems

Q-learning, a model-free RL algorithm, learns optimal policies through state-action-reward interactions[25]. Applied to parameter optimization

$$Q(s_t, a_t) \leftarrow Q(s_t, a_t) + \alpha[r_t + \gamma \max_a Q(s_{t+1}, a') - Q(s_t, a_t)]$$

Recent applications in distributed systems include resource allocation and job scheduling optimization[26].

3. Proposed Framework Architecture and Methodology

3.1 Overall System Architecture

The comprehensive framework comprises five integrated components

Component 1: Genetic Programming Module Analyzes empirical MapReduce execution data (input size, task counts, CPU/memory utilization) to automatically derive mathematical fitness functions capturing parameter relationships. GP generates function trees combining terminal parameters (g1-g8) with arithmetic operations (+, -, ×, ÷).

Component 2: Feature Selection and Parameter Ranking Applies machine learning algorithms (random forest, gradient boosting) to historical parameter-performance data identifying critical parameters from 190+ candidates. Feature importance ranking reveals parameter impact on execution time.

Component 3: Ensemble Prediction Model Trains multiple learners (random forest, gradient boosting, XGBoost) on parameter-execution time dataset. Ensemble approach combines predictions through weighted averaging, achieving high accuracy ($R^2 = 0.94$).

Component 4: Genetic Algorithm Optimizer Implements advanced GA with roulette wheel selection, single-point crossover, adaptive mutation. Searches parameter space guided by GP-derived fitness function. Population 15×200 generations achieves convergence within 40,000 evaluations.

Component 5: Reinforcement Learning Adapter Monitors actual job performance, compares with predictions, updates Q-values. Enables runtime parameter adjustment for dynamic cluster conditions.

3.2 Genetic Programming for Fitness Function Derivation

The fitness function generation process follows these steps

3.2.1 Step 1: Data Collection Execute representative MapReduce jobs with varied parameter configurations

- Jobs: WordCount, Grep, Index, TeraSort on 1GB-10GB datasets

- Parameters: 8 critical parameters with ranges from Table 1
- Metrics: Job completion time, resource utilization, network bandwidth

Step 2: GP Tree Construction Genetic programming builds expression trees

$$f(g_1, g_2, \dots, g_8) = (g_3 + g_7) \times \frac{g_5}{g_2} + (g_1 \times g_6) - (g_4 + g_8)$$

(Equation 3.1)

where:

- g_1 : mapreduce.task.io.sort.mb
- g_2 : mapreduce.task.io.sort.factor
- g_3 : mapred.compress.map.output(boolean: 0/1)
- g_4 : mapreduce.job.reduces
- g_5 : mapreduce.map.sort.spill.percent
- g_6 : mapreduce.tasktracker.map.tasks.maximum
- g_7 : mapreduce.tasktracker.reduce.tasks.maximum
- g_8 : mapreduce.reduce.shuffle.input.buffer.percent

Step 3: Fitness Evaluation For each candidate function, calculate error between predicted and actual execution times

$$\text{Error} = \frac{1}{n} \sum_{i=1}^n |f_{\text{predicted}}(i) - f_{\text{actual}}(i)| \quad (\text{Equation 3.2})$$

Step 4: GP Evolution Apply crossover and mutation to best-performing functions, iterating until convergence.

3.3 Machine Learning-Based Parameter Selection

Random forest feature importance ranking identifies critical parameters:

$$FI_j = \frac{\sum_{\text{trees}} \text{Information Gain}_j}{\text{Total Information Gain}} \quad (\text{Equation 3.3})$$

Parameters ranked by importance score; eight parameters with highest importance selected:

- mapreduce.task.io.sort.mb (importance: 0.28)
- mapreduce.job.reduces (importance: 0.22)
- mapreduce.tasktracker.map.tasks.maximum (importance: 0.18)
- mapreduce.reduce.shuffle.input.buffer.percent (importance: 0.15)
- mapreduce.task.io.sort.factor (importance: 0.08)
- mapreduce.map.sort.spill.percent (importance: 0.05)
- mapreduce.tasktracker.reduce.tasks.maximum (importance: 0.03)
- mapred.compress.map.output (importance: 0.01)

3.4 Ensemble Prediction Model

Three base learners are trained on parameter-performance dataset

Random Forest Model

$$\hat{y}_{\text{RF}} = \frac{1}{B} \sum_{b=1}^B T_b(\mathbf{x})$$

where represents individual tree predictions.

Gradient Boosting Model

$$\hat{y}_{\text{GB}} = \sum_{m=0}^M \gamma_m h_m(\mathbf{x})$$

where are weak learners trained on residuals.

XGBoost Model

$$\hat{y}_{\text{XGB}} = \sum_{m=1}^M f_m(\mathbf{x})$$

Ensemble Prediction

$$\hat{y}_{\text{ensemble}} = w_1 \hat{y}_{\text{RF}} + w_2 \hat{y}_{\text{GB}} + w_3 \hat{y}_{\text{XGB}} \quad (\text{Equation 3.4})$$

where weights are learned through cross-validation.

3.5 Genetic Algorithm Optimization

The GA implementation follows standard evolutionary algorithm paradigm

3.5.1 Step 1: Initialization Initialize population with random chromosomes

$$\text{Chromosome}_i = [g_{i,1}, g_{i,2}, g_{i,3}, g_{i,4}, g_{i,5}, g_{i,6}, g_{i,7}, g_{i,8}] \quad (\text{Equation 3.5})$$

where each gene represents parameter value within specified range (Table 1).

Population size: 15 chromosomes Generations: 200

3.5.2 Step 2: Fitness Evaluation For each chromosome, evaluate fitness using GP-derived function (Equation 3.1) $f_i = f(g_{i,1}, g_{i,2}, \dots, g_{i,8})$

3.5.3 Step 3: Selection - Roulette Wheel Method

Fitness probability for chromosome

$$FP_i = \frac{f_i}{\sum_{j=1}^N f_j} \quad (\text{Equation 3.6})$$

Lower fitness values indicate better configurations (minimization problem). Roulette wheel selection assigns selection probability proportional to fitness, with low-fitness chromosomes having higher selection probability.

3.5.4 Step 4: Crossover Operation

Single-point crossover with rate $P_c = 0.2$ (20%):

For chromosomes selected for crossover, randomly select crossover point $k \in [1, 7]$

$$\text{Offspring1} = [g_1^A, \dots, g_k^A, g_{k+1}^B, \dots, g_8^B]$$

$$\text{Offspring2} = [g_1^B, \dots, g_k^B, g_{k+1}^A, \dots, g_8^A] \quad (\text{Equation 3.7})$$

This genetic operator enables information exchange between successful solutions.

3.5.5 Step 5: Mutation Operation

Mutation rate: $P_m = 0.1$ (10%)

For each gene selected for mutation, replace with random value within parameter range

$$g'_j = \text{random}(\min_j, \max_j) \quad (\text{Equation 3.8})$$

Expected number of mutations per generation

4. Experimental Results and Analysis

4.1 WordCount Application Performance

Table 3. WordCount Application - Execution Time Comparison

Dataset	Default	Proposed	Speedup	Improvement
Size (GB)	(sec)	(sec)	Factor	(%)
1	1450	535	2.71	63.10
5	1680	520	3.23	69.05
10	1850	580	3.19	68.65
Average	1660	545	3.04	66.93

Analysis: Word Count achieves highest improvement (average 66.93%) due to CPU-intensive nature benefiting from optimal map task allocation and compression parameters.

4.2 TeraSort Application Performance

Table 4. TeraSort Application - I/O Performance Analysis

Dataset	Default	Proposed	Speedup	Improvement
Size (GB)	(sec)	(sec)	Factor	(%)
1	620	290	2.14	53.23
5	750	365	2.05	51.33

$0.1 \times 8 \times 15 = 12$ mutations.

3.5.6 Step 6: Convergence Criteria

Algorithm terminates when

- Maximum generations (200) reached, OR
- Fitness improvement over 10 consecutive generations

3.6 Reinforcement Learning for Dynamic Adaptation

Q-learning monitors actual job execution and adjusts recommendations

State Space Definition

$$s_t = \{\text{JobType}, \text{DataService}, \text{CPU_Util}, \text{Memory_Util}, \text{Network_BW}\}$$

Action Space

$$A = \{\text{Increase}, \text{Maintain}, \text{Decrease}\} \times \{\text{Parameter}_1, \dots, \text{Parameter}_8\}$$

Reward Function

$$R_t = \begin{cases} \frac{ET_{\text{predicted}} - ET_{\text{actual}}}{ET_{\text{predicted}}} & \text{if } ET_{\text{actual}} < ET_{\text{predicted}} \\ -0.5 & \text{otherwise} \end{cases} \quad (\text{Equation 3.9})$$

Q-Value Update

$$Q(s_t, a_t) \leftarrow Q(s_t, a_t) + \alpha [R_t + \gamma \max_a Q(s_{t+1}, a') - Q(s_t, a_t)] \quad (\text{Equation 3.10})$$

where learning rate $\alpha = 0.1$, discount factor $\gamma = 0.95$.

10	850	380	2.24	55.29
Average	740	345	2.14	53.28

Analysis: *TeraSort improvement (53.28% average) reflects I/O-intensive nature; benefits primarily from io.sort.mb and shuffle buffer optimization.*

4.3 Grep Application Performance

Table 5. Grep Application - Mixed Workload Performance

Dataset	Default	Proposed	Speedup	Improvement
Size (GB)	(sec)	(sec)	Factor	(%)
1	1800	800	2.25	55.56
5	1950	960	2.03	50.77
10	2100	1110	1.89	47.14
Average	1950	957	2.06	51.16

4.4 Index Application Performance

Table 6. Index Application - Comprehensive Performance

Dataset	Default	Proposed	Speedup	Improvement
Size (GB)	(sec)	(sec)	Factor	(%)
1	1550	450	3.44	70.97
5	1700	820	2.07	51.76
10	1850	1030	1.80	44.32
Average	1700	767	2.44	55.68

4.5 Genetic Algorithm Convergence Analysis

Table 7. GA Convergence Characteristics (Lower Fitness = Better)

Generation	Best Fitness	Avg Fitness	Diversity
1	450	650	0.92
20	280	380	0.68
50	245	320	0.52
100	210	280	0.38
150	198	270	0.25
200	195	268	0.18

Convergence Insight: Algorithm converges within 100 generations (50% completion); continues refinement through generation 200, improving best fitness from 450 to 195 (57% improvement).

4.6 Fitness Function Accuracy

Table 8. Fitness Function Prediction Accuracy

Application	R ² Value	RMSE (sec)	Accuracy
WordCount	0.91	42	91.2%
TeraSort	0.89	38	89.1%
Grep	0.87	45	87.3%
Index	0.88	41	88.2%
Overall	0.89	41.5	89.0%

5. Conclusion

This research proposes an intelligent hybrid framework for Hadoop MapReduce parameter tuning using genetic programming, parallel genetic algorithms, ensemble machine learning, and reinforcement learning. Automatic fitness function generation achieves high accuracy ($R^2 = 0.89$), while ensemble

models reach over 94% prediction performance. Q-learning enables dynamic adaptation of parameters under changing cluster conditions. Extensive experiments on WordCount, Grep, TeraSort, and Index with 1–10 GB datasets validate the approach. The framework delivers an average $2.35\times$ speedup and 57.5% reduction in execution time over default settings.

Overall, the method provides a scalable and efficient solution for automated big data performance optimization.

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